

Developments at SLAC

C. Kenney, R. Herbst, B. Duda, L. Manger, T. Nieland, J. Tice, P. Hart, M. Weaver, J. Pines, G. Haller, N. van Bakel, J. Morse, S. Veljovic, M. Swift, M. Nordby, G. Williams, S. Boutet, D. Fritz, M. Cammarata, T. Fornek, S. Moeller, N. Kurita, J. Langdon, D. Schafer, M. Carrasco, E. Perozzeillo, A. Dragone, P. Caragiulo, J. Segal

Extensive collaborations with other institutions

Gratefully acknowledge support by DOE and NIH



CS-PAD Camera

Successful collaboration with Cornell University

110 mm by 110 mm by 500 mm thick pixels

Array of 758 by 758 pixels

Readout at 120 Hz using RCE-based DAQ

High and Low Gain modes

Bump-bonded, hybrid architecture



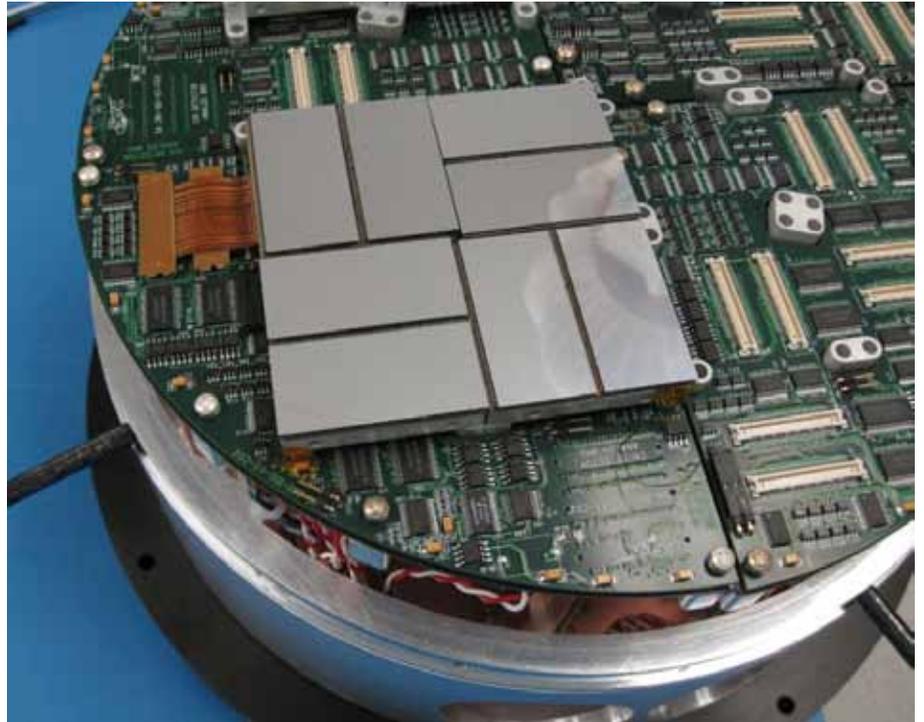
Cornell Team

Darol Chamberlain (2), Sol M. Gruner (1,2),
Marianne S. Hromalik (1,3), Lucas J. Koerner
(1,4), Hugh T. Philipp (1), Mark W. Tate (1)(1)
Department of Physics, Cornell University(2)
Cornell High Energy Synchrotron Source (CHESS)
(3) presently SUNY Oswego(4) presently Applied
Physics Lab of Johns Hopkins University

XPP Hutch

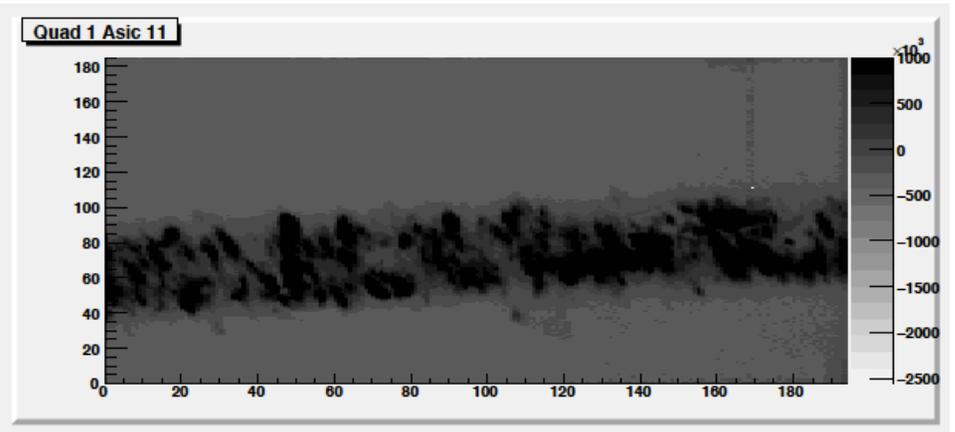
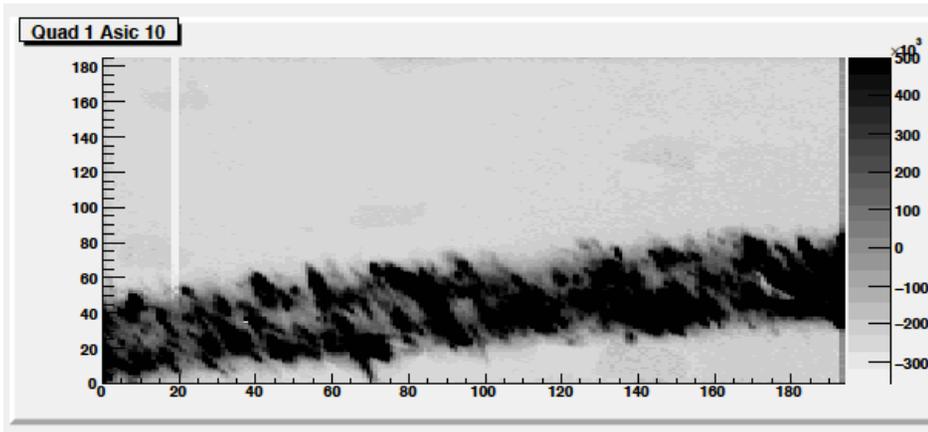
Only quarter of possible modules mounted

Partially due to bump bond yield



Being installed on XPP robot arm
by Ryan Herbst

CS-PAD Sees First LCLS Light



August 26

Beryllium window target

~ 9 keV photons

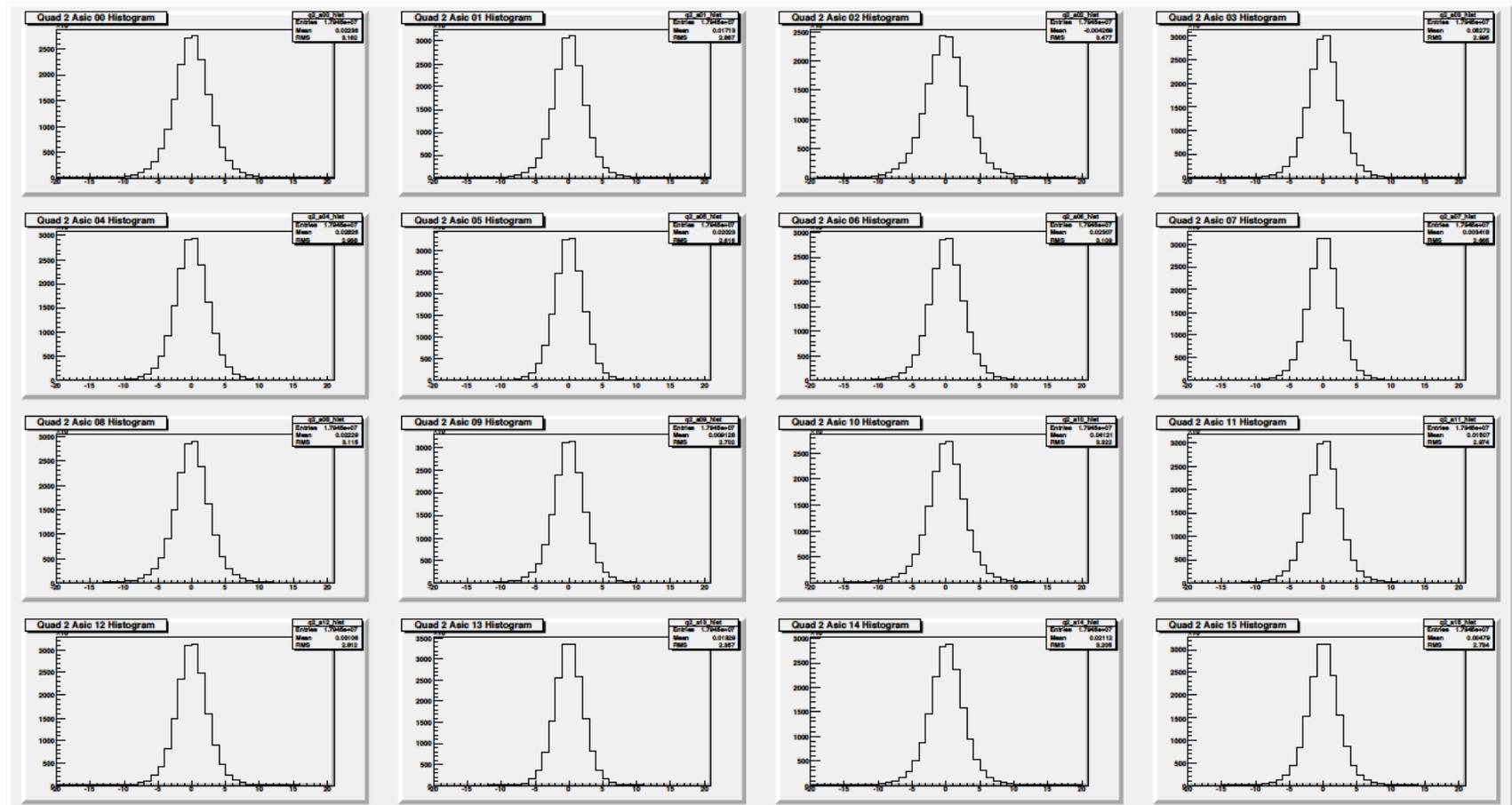
~ 1 mJ per pulse

Operated under-biased at 40 V
for safety reasons

CS-PAD Noise

Noise distributions for each of the 16 ASICs as measured in the XPP hutch on the robot arm

Typical RMS of 3 ADUs



CS-PAD in XPP Thermal

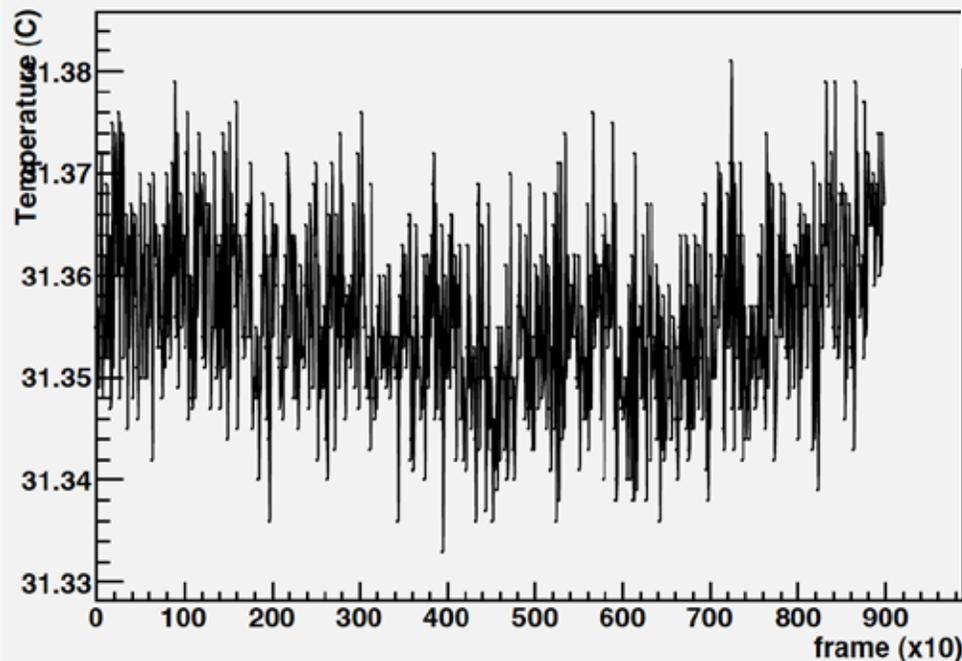
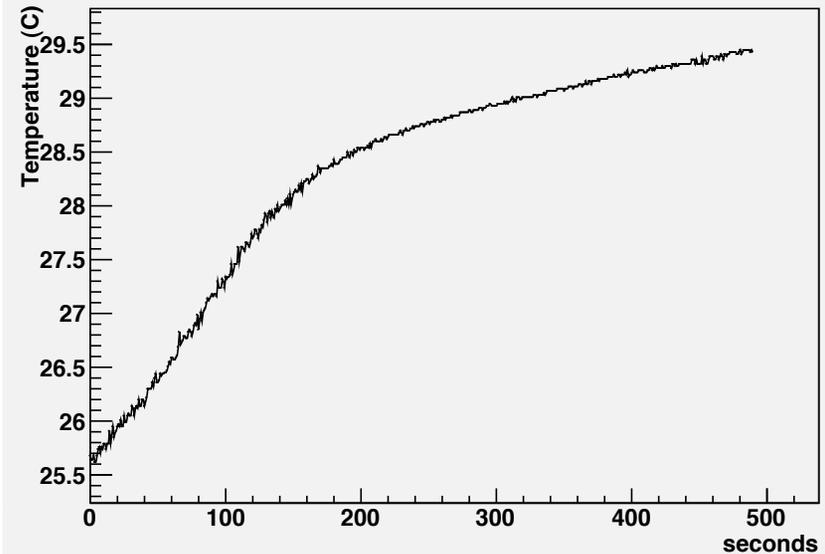
In air

Water cooled

Equilibrates in 30 minutes

Stable to within +/- 10 mK
over 15 minutes

Temperature History



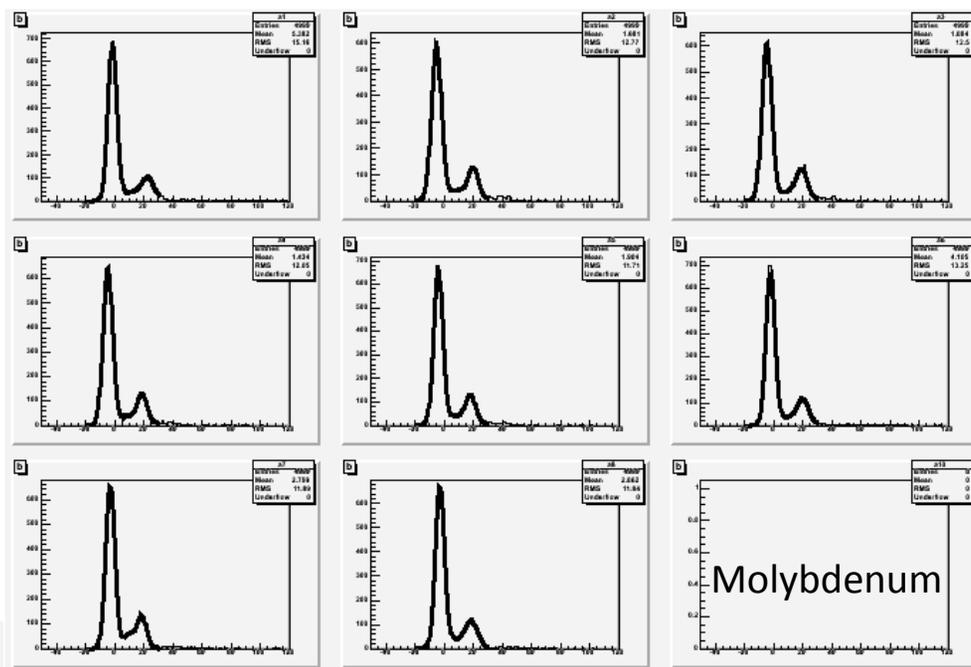
Solid copper cold straps
Sensor around 37 C

CS-PAD Spectra/Gain

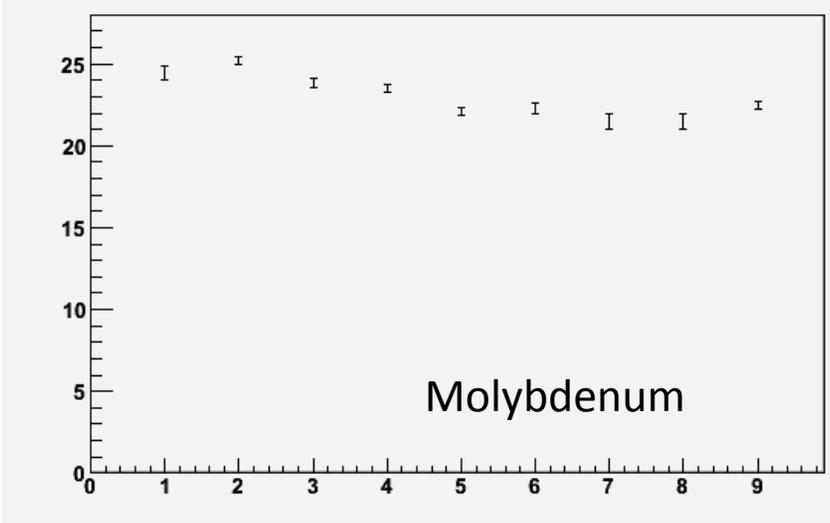
X-ray fluorescence spectra: Cu, Se, Mo

Taken at ALS

Used to provide pixel-by-pixel gain correction

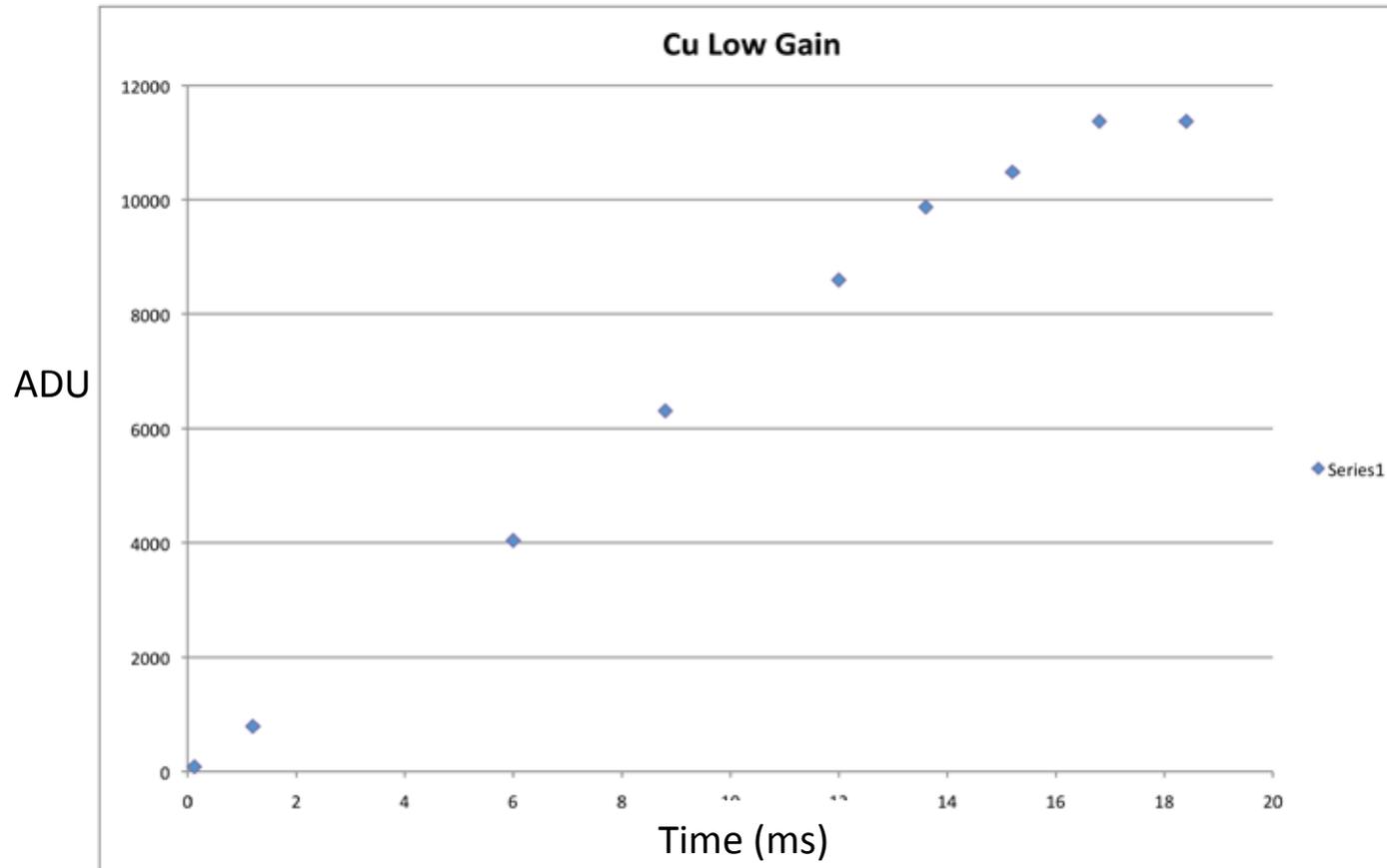


Distance Peaks vs Pixels w. errors



On average 8 keV photon equals 10.5 ADUs

CS-PAD Dynamic Range



Full capacity in low gain mode is over 7,000
8 keV photons

Taken at ALS 10.3.1

CS-PAD Frame Noise

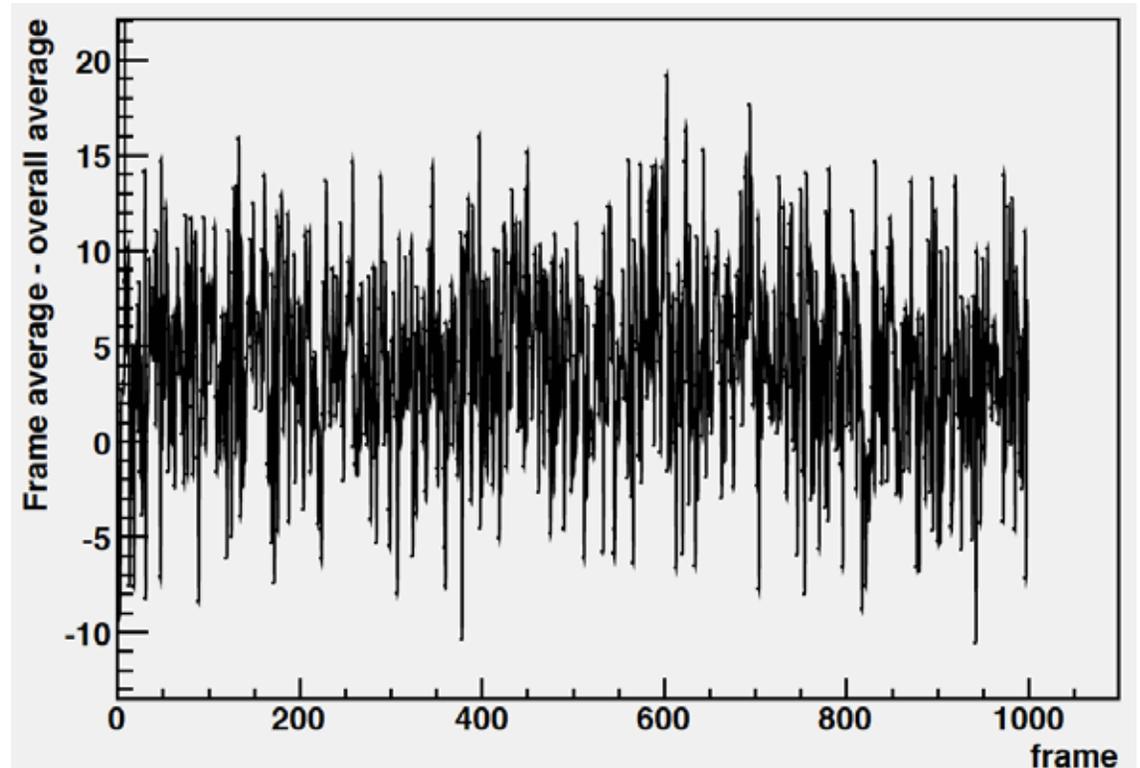
Correlated across one ASIC

Varies frame-to-frame

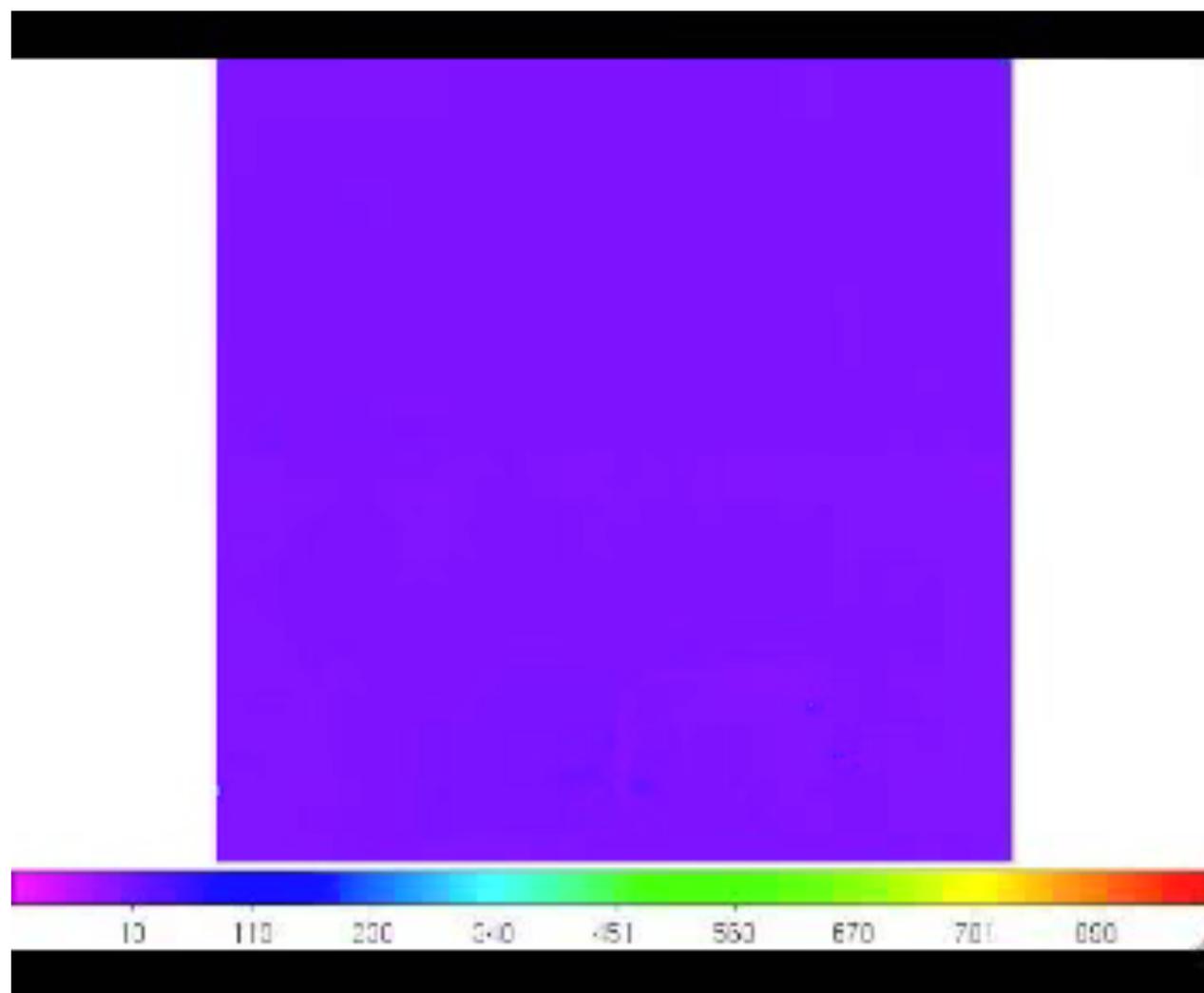
Low occupancy – correctable

Very high occupancy – insignificant

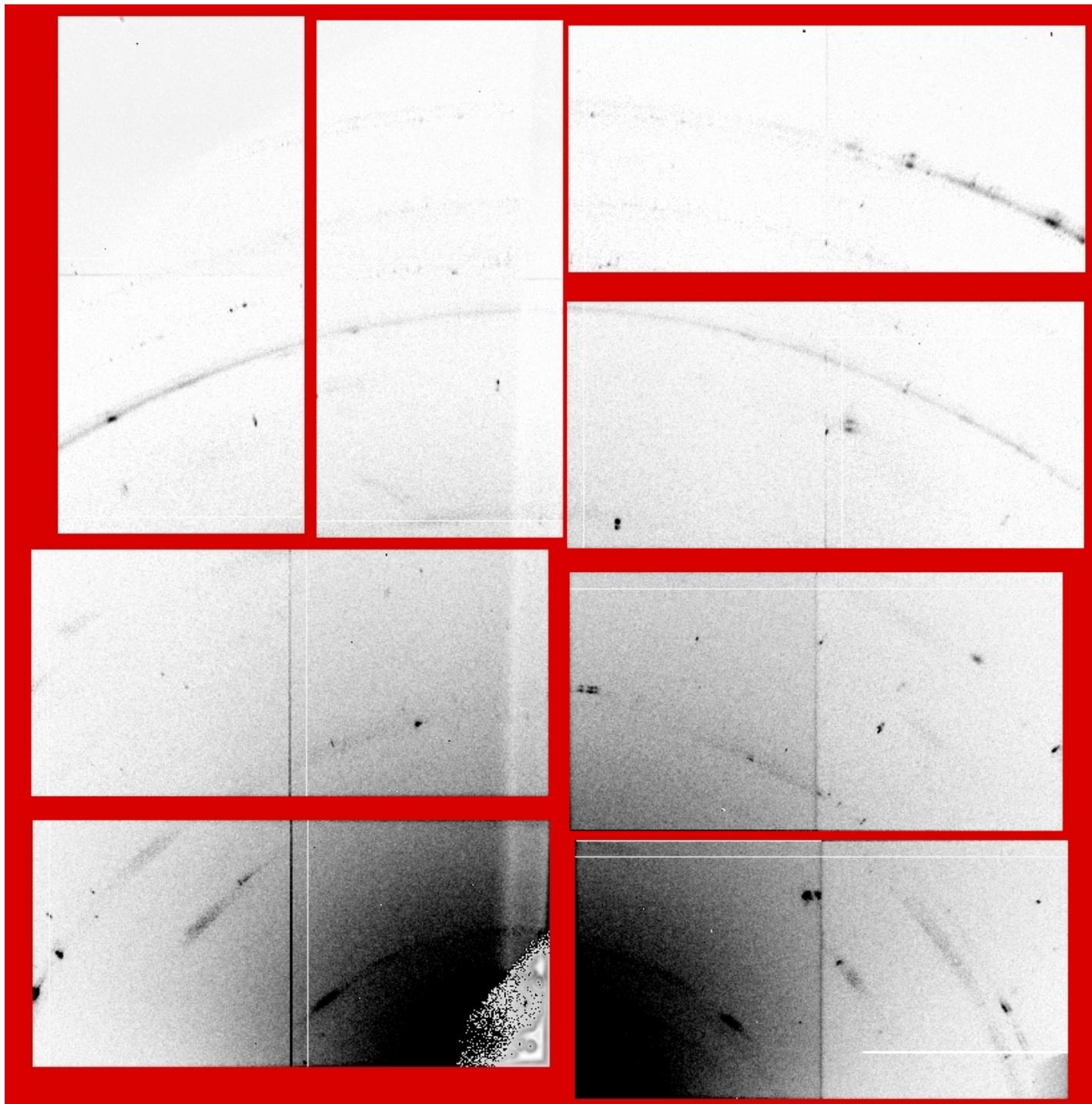
Disconnect 20 pixels to provide references (i.e. no bump between circuit cell and sensor cell)



LCLS Silver Behenate



Silver
Behenate
powder



CS-PAD in XPP

Much work left to do:

Calibration software

Modules for remainder of camera

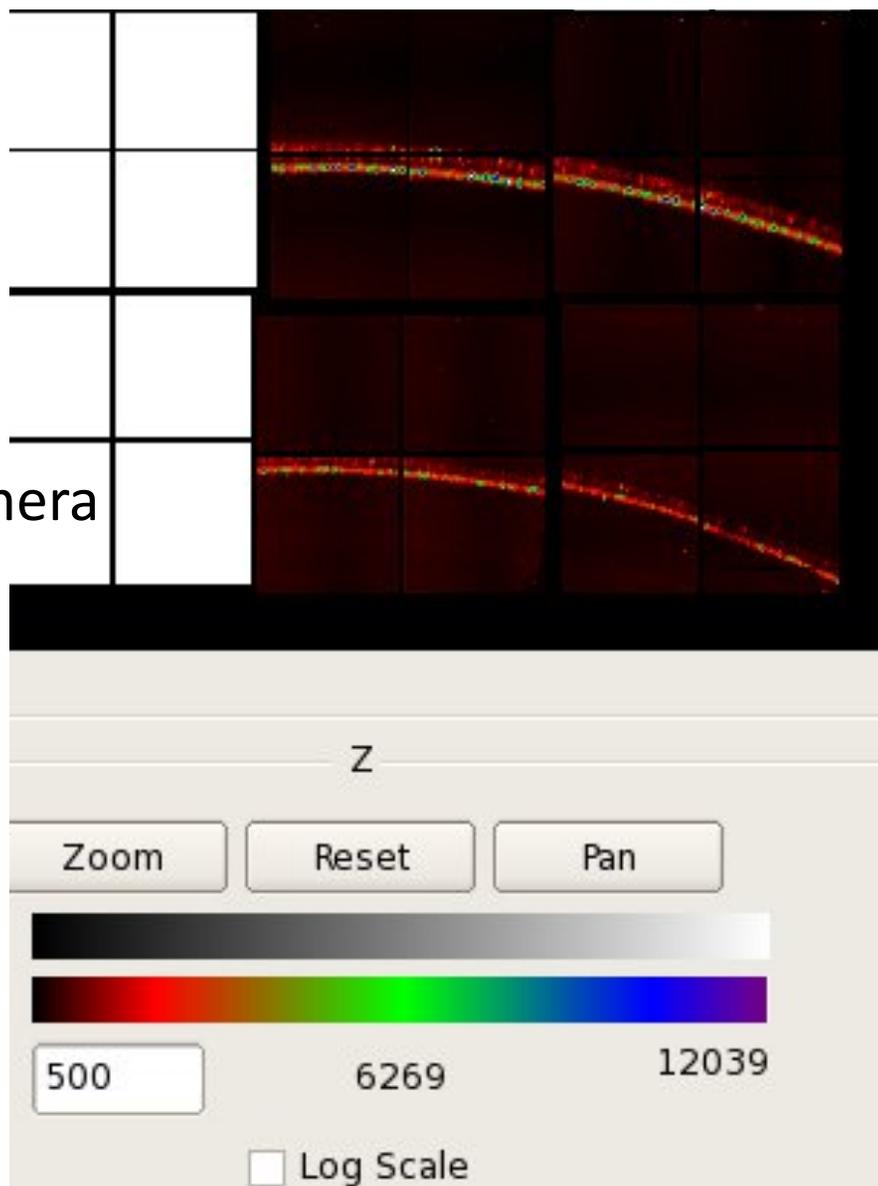
Beryllium window

9 keV

~1 mJ/pulse

High gain mode

Raw data



CXI Hutch

Same modules as used in XPP hutch

Operate in vacuum

Two full cameras needed

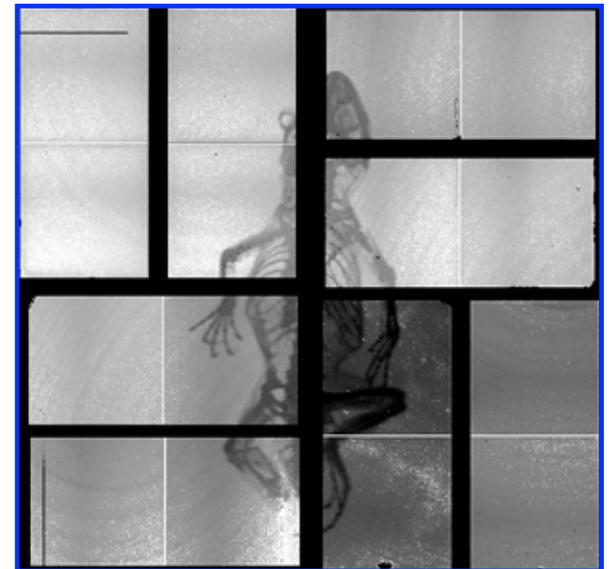
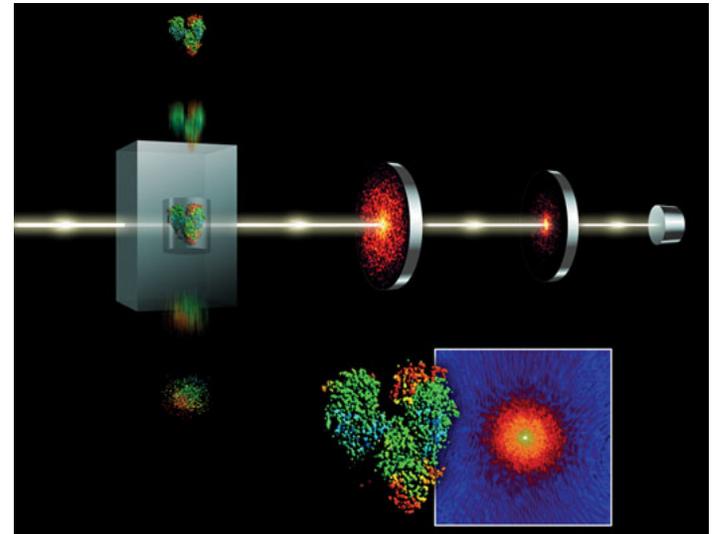
Variable aperture

Second camera mechanical assembly nearly complete

Progress being made in design of the flexible cold straps

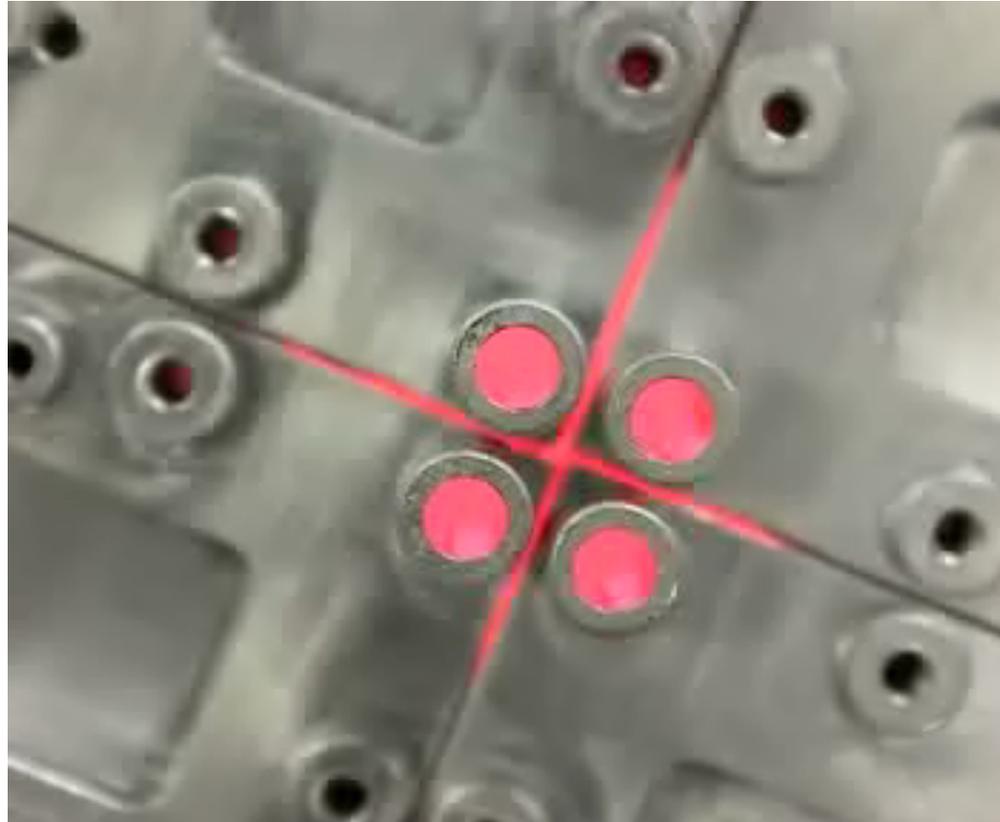
Sufficient ASICs and sensors either on hand or on order

Challenges: bump bonding, assembly, testing, cold straps



CXI Variable Aperture

B. Duda
T. Nieland



BNL XCS Sensor Concept

Small pixel (< 60 μm)

Low noise (< 100 electrons)

Modest full well capacity (100 x 8 keV)

Charge pump design is proposed

Central anode surrounded by three rings

Modulate the potentials on the 4 electrodes so that:

Signal charge is collected on the middle P-ring during the sensing stage

Signal charge is transferred to the anode during the readout stage

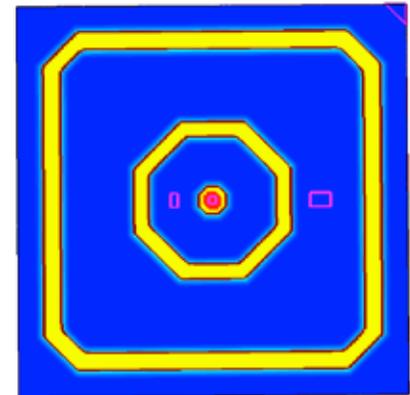
BNL:

Pavel Rehak

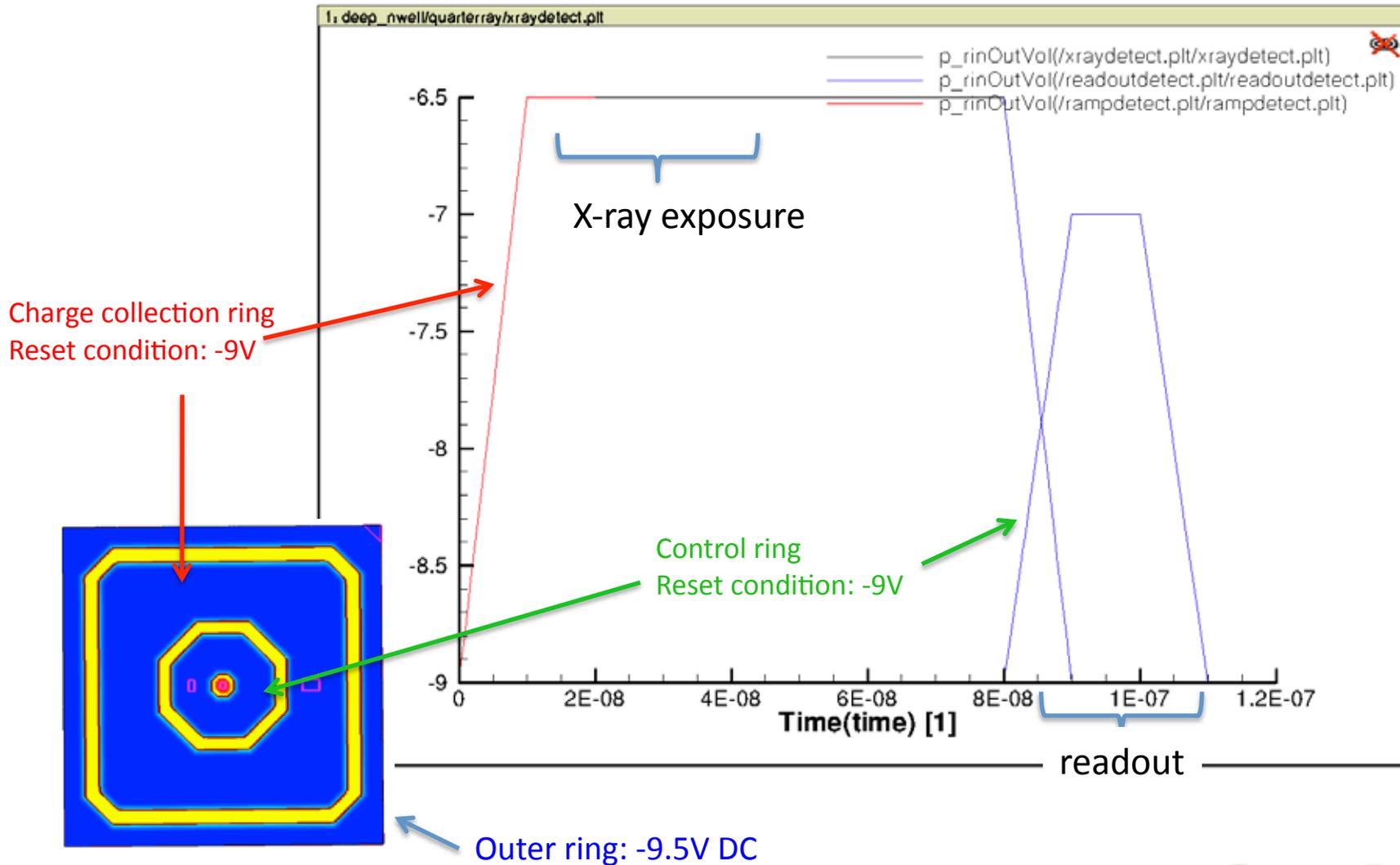
Gabriella Carini

Wei Chen

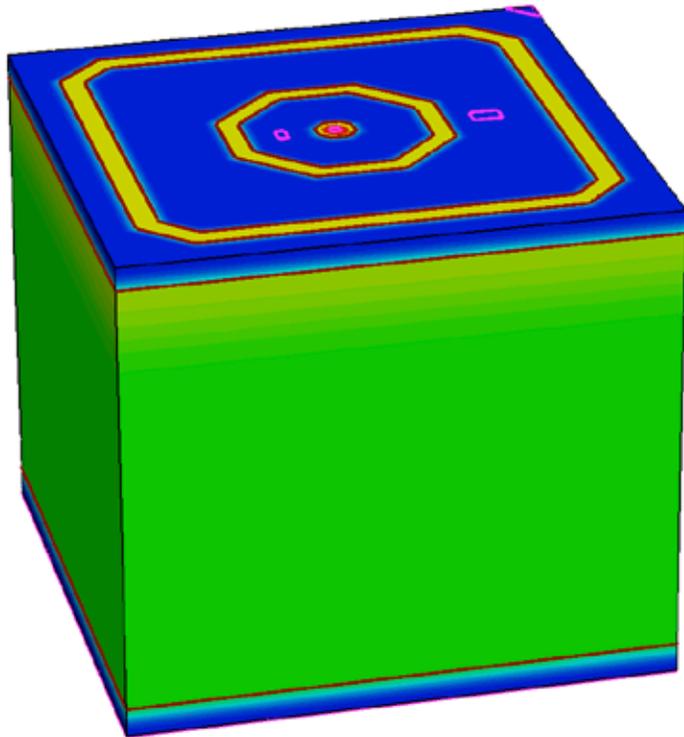
Pete Siddons



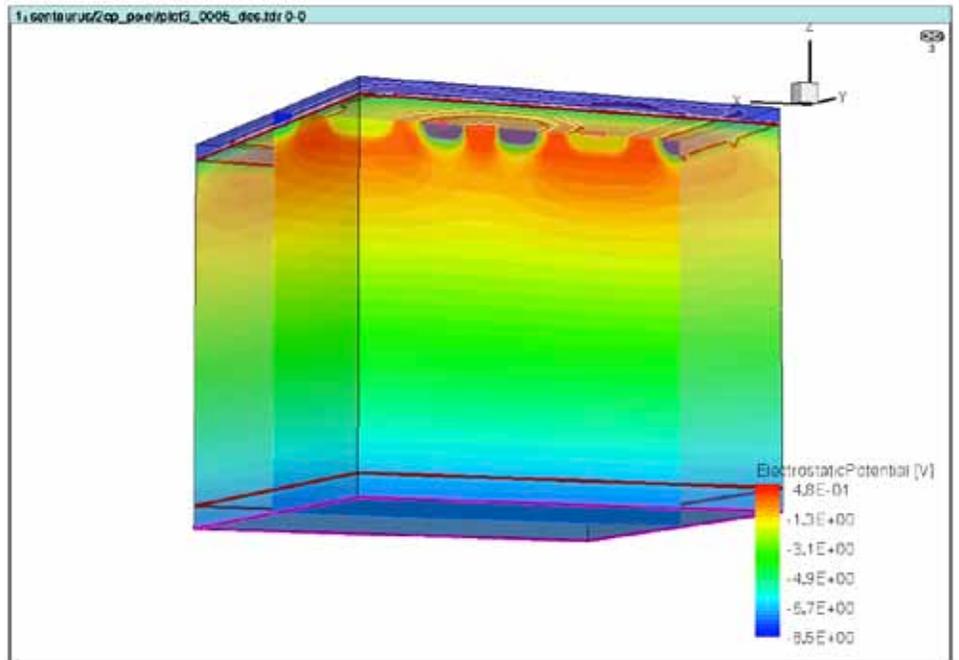
Pixel Bias Sequence



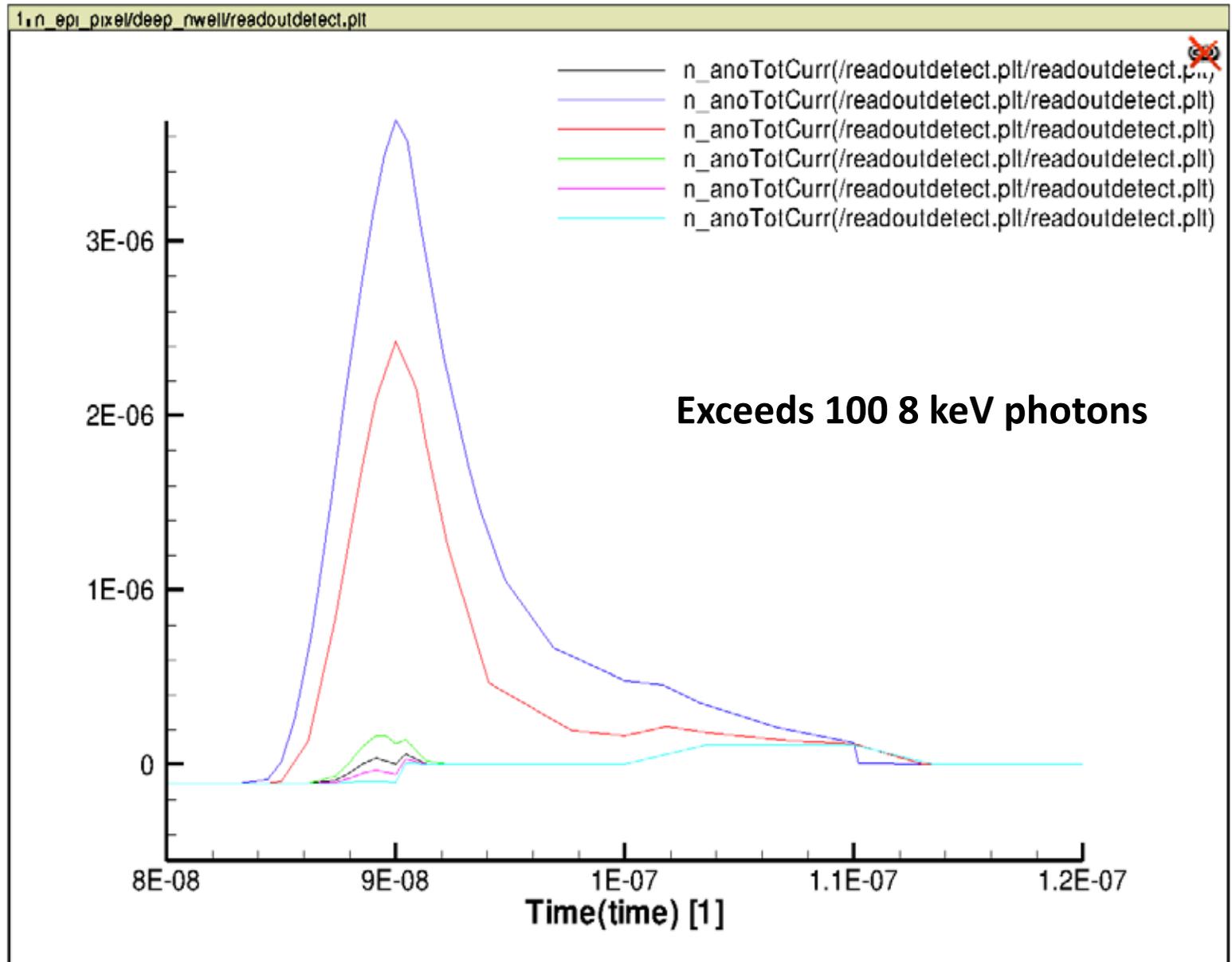
3D Simulations



Julie Segal
Synopsys TCAD



XCS Sensor Full Capacity

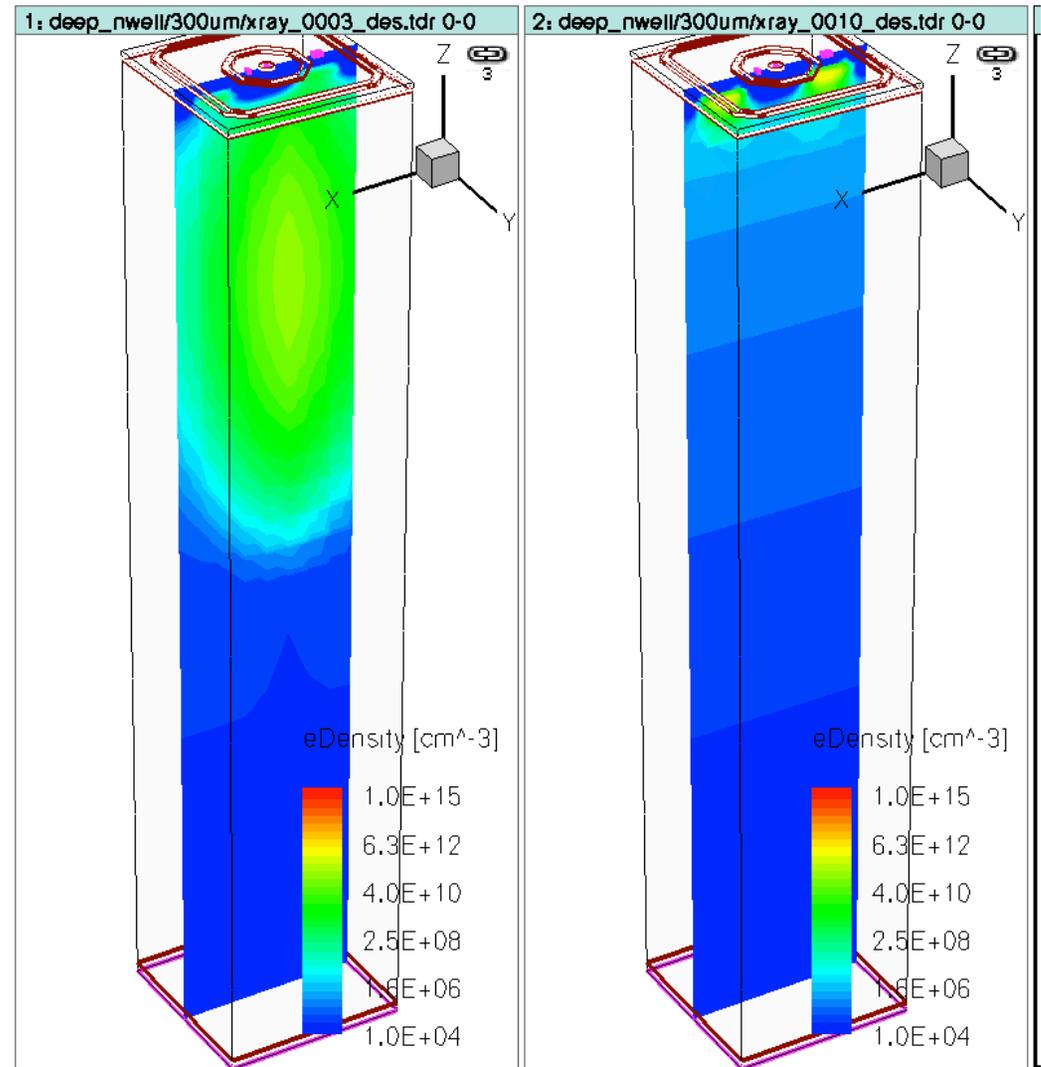


Signal Collection

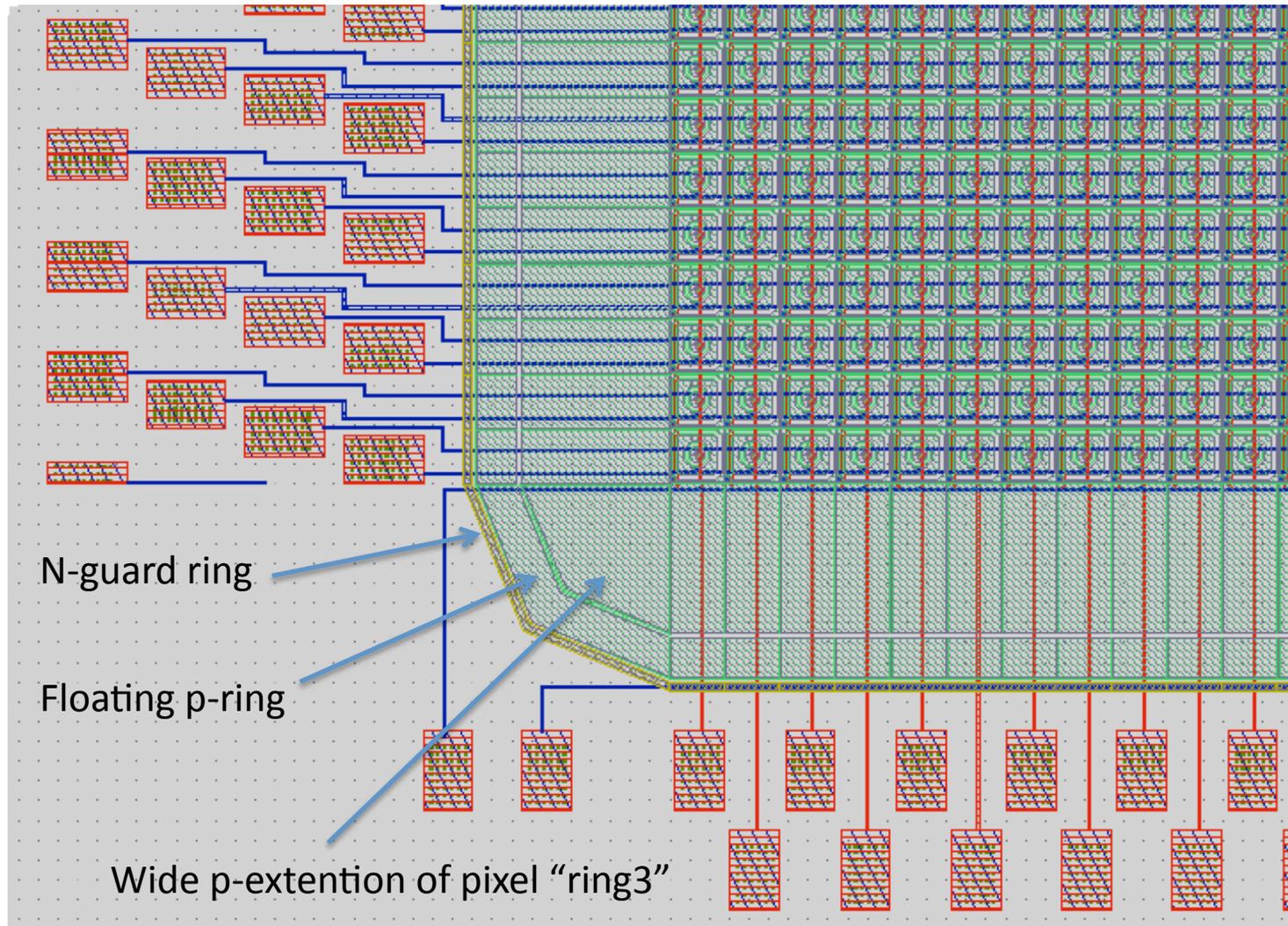
8 keV photon

Charge 5 ns and 50 ns
after x-ray absorbed

Electrons are collected
under middle P ring



XCS Sensor Layout



ASML Stepper

PAS-5500/60
I Line (365 nm)

Overlay accuracy is 20 nm

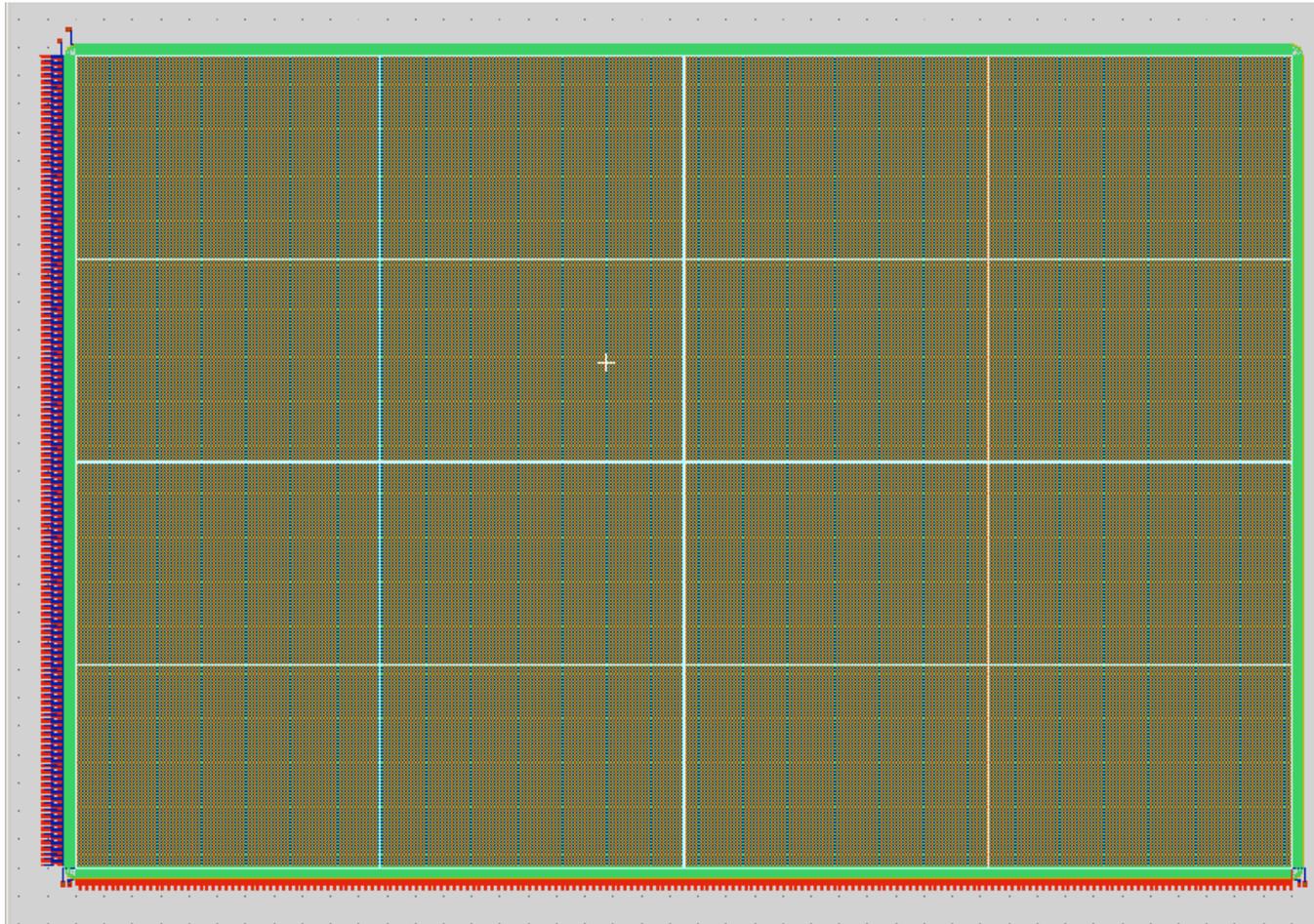
Features down to 400 nm

Maintained by ASML
engineers on a daily basis

Can program sensor array
sizes on the fly – no need to
purchase new stepper masks



XCS 384 x 256 Sensor



28 Exposures

XCS Manufacture

Full process simulation complete

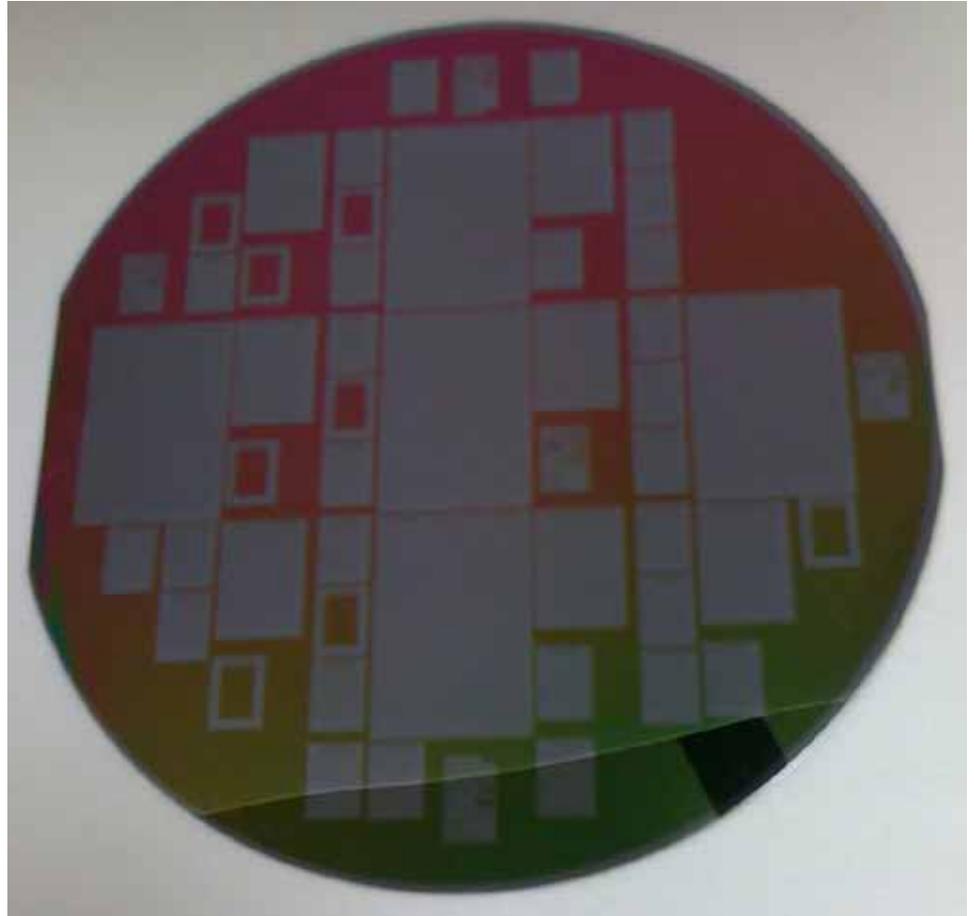
Wafer fabrication has begun

Ten 300 mm thick wafers

Five 500 mm thick wafers

Mask design finished

Masks in hand

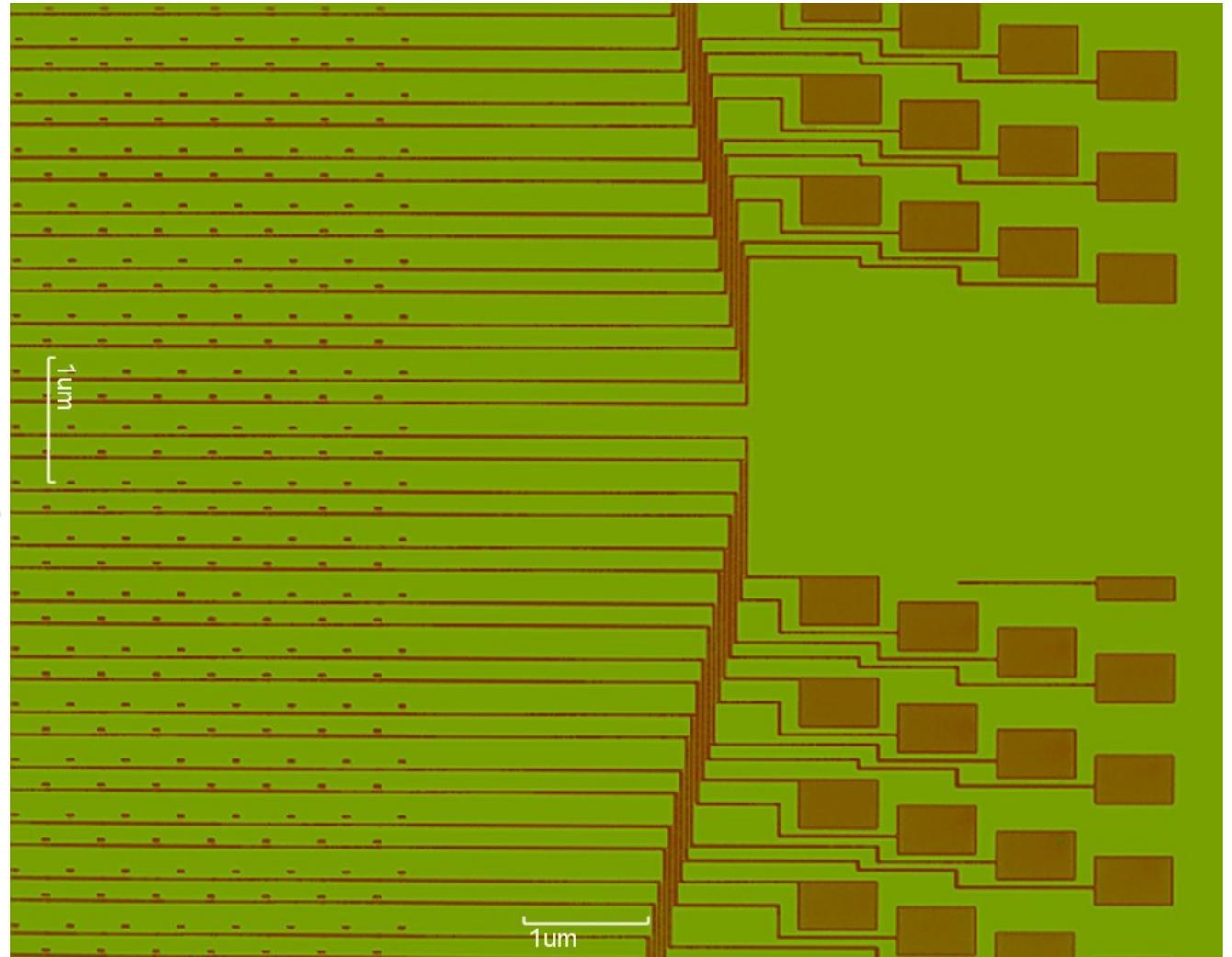


XCS Switcher Pads

Stitched field

2 micron lines

Can you locate the stitching seam?



XCS Switcher

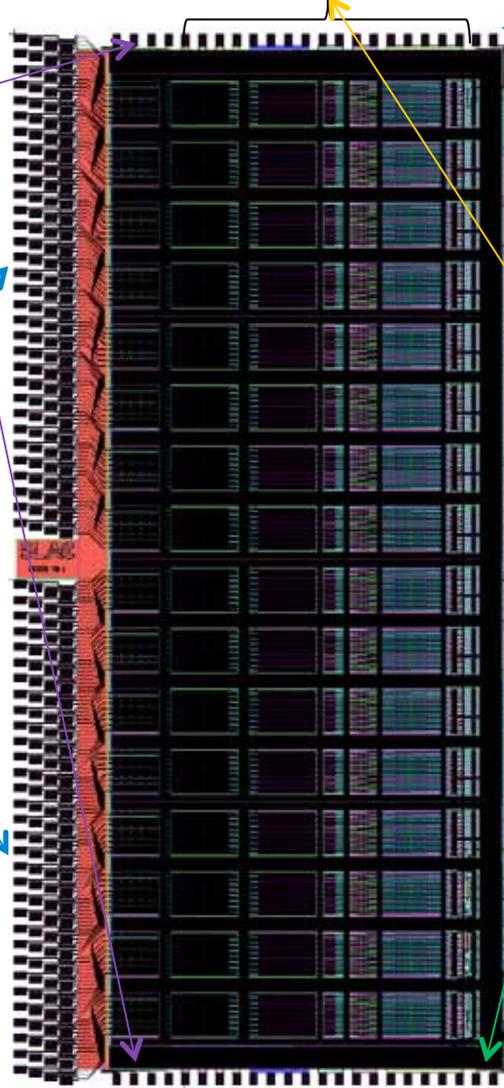
A. Dragone¹, G. Haller¹, and P. Caragiulo²
¹SLAC National Accelerator Laboratory
²DEE Polytechnic Institute of Bari

Monitor for the first and last 4 channels

Output 128 dual channels
56 um pitch

Technology: TSMC 0.18um HV LDD-MOS

Average Power Consumption with
the expected settings ~ 100mW/per chip



Token bidirectional
(redundant – top and bottom
for daisy chain)

Drives the P rings
Swings from -30V to +30V

Supplies (redundant pads)

Control Lines

XCS System

Modular

Operate at -40 C

Minimize insensitive gaps

As large an area as possible

Mechanical design in early stages

Expect to operate complete prototype in early 2011



MEC Hutch

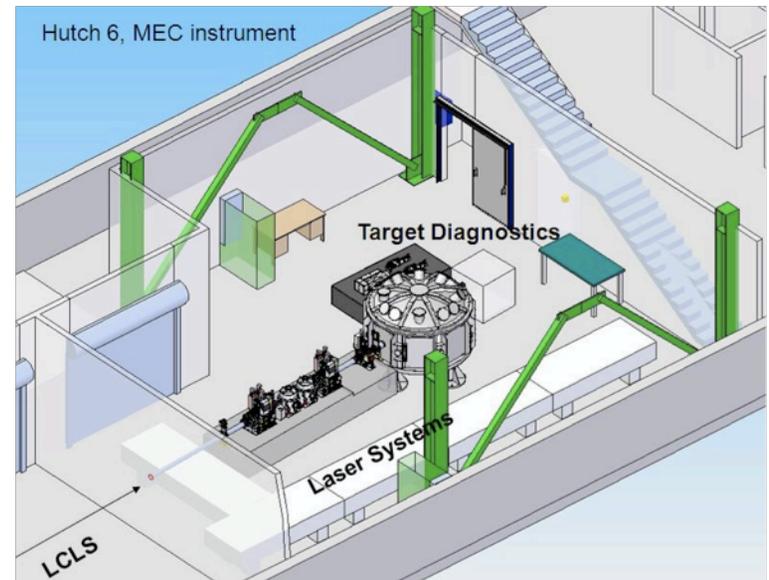
Small camera

Core is CS-PAD

Two 2x2 modules

Thinner aluminum entrance window

Needed late 2011



FEXAMPS for XCS Beamfinder

Requirements similar to those of the XPP camera:

Large dynamic range ~ 14 bits

Noise $<$ single photon

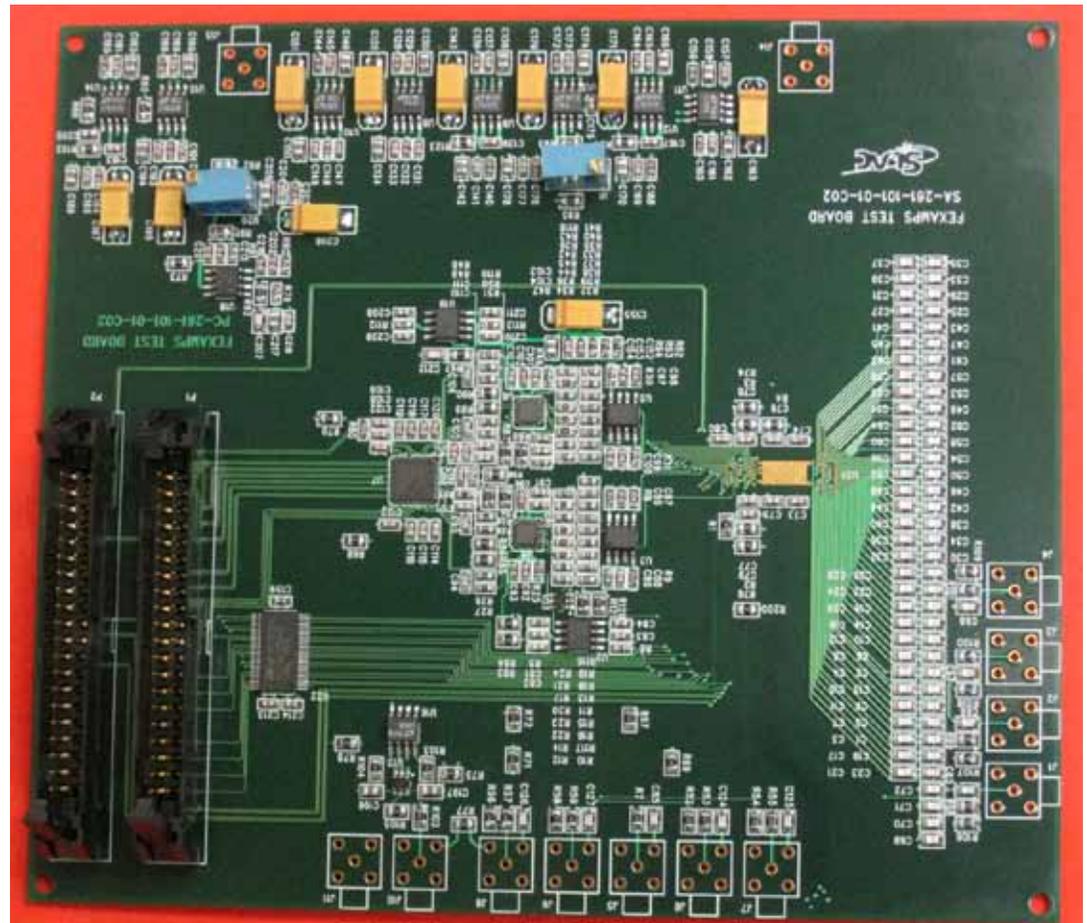
Area ~ 1 mm²

Low channel count = strips ...

Efficient for 6 – 25 keV photons

Working on new DAQ board

SLAC: A. Dragone
BNL: P. O'Connor



Molecular Biology Consortium:

E. Westbrook and A. Thompson

University of Hawaii: S. Parker

LBNL:

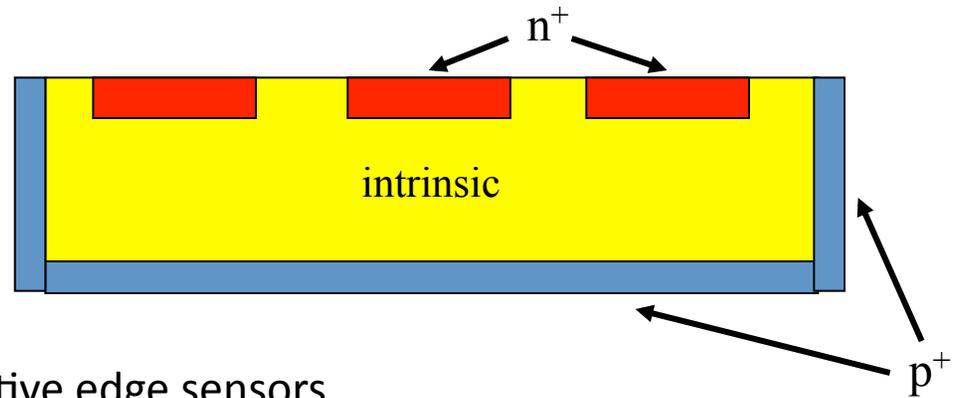
E. Mandelli, G. Meddeler, D. Gnani

Stanford University:

N. Jaffari, B. Wooley

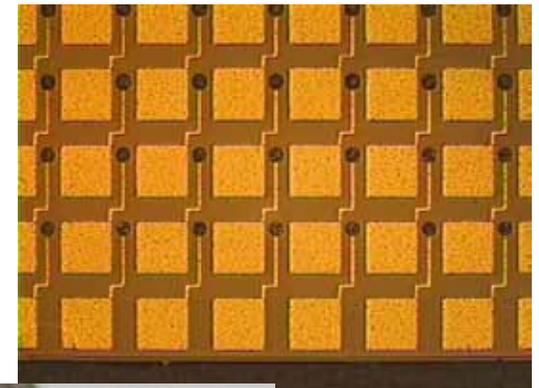
ESRF: J. Morse

3DX

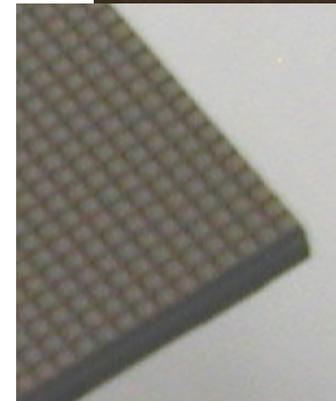
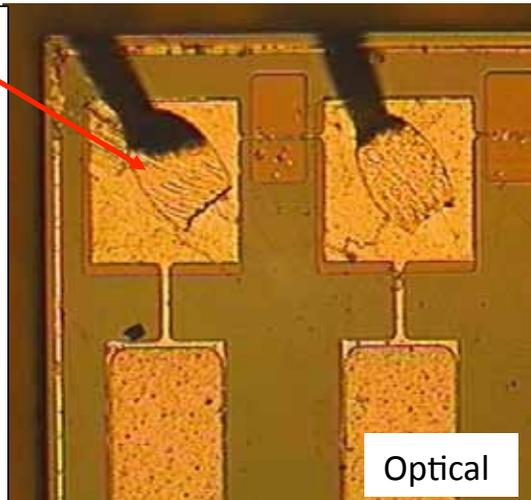
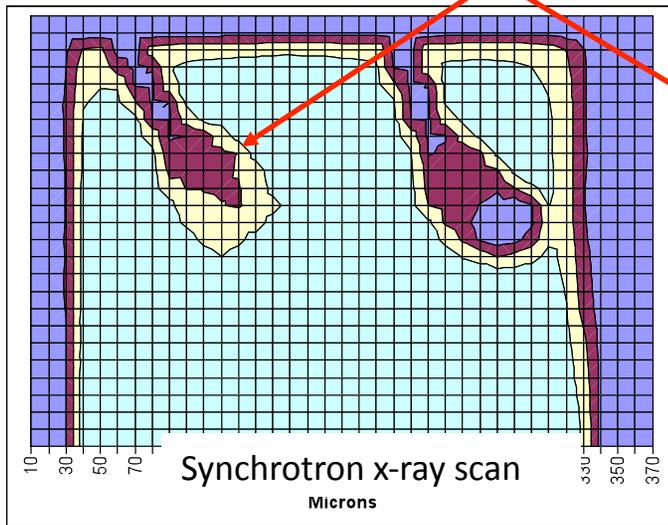


Active edge sensors

150 mm square pixels

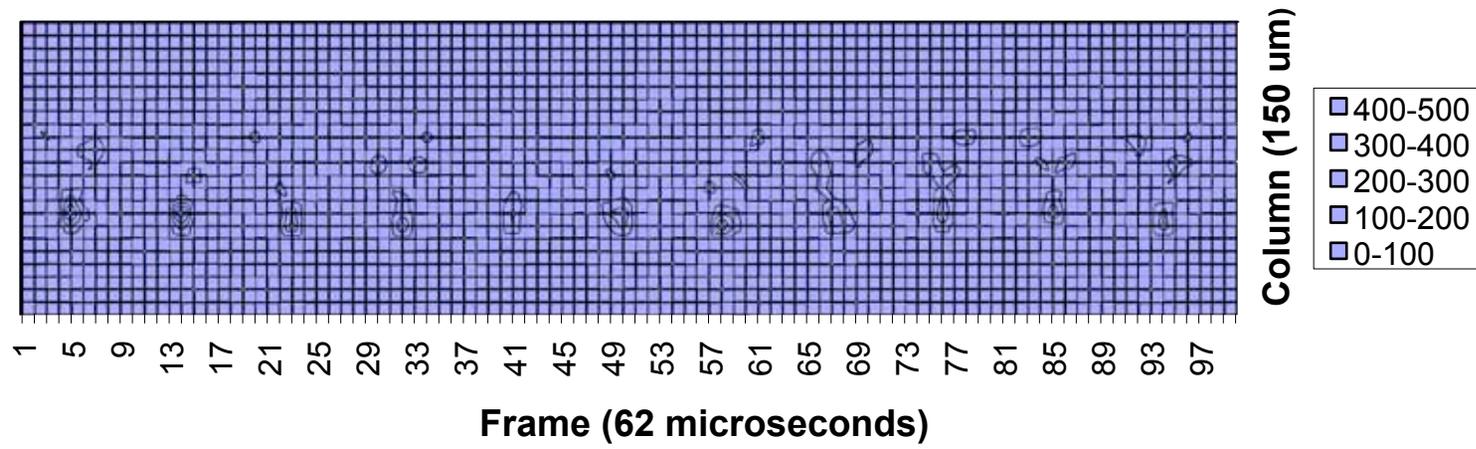


Wire bonds



Bump
Bonded at
Stanford

3DX Timing

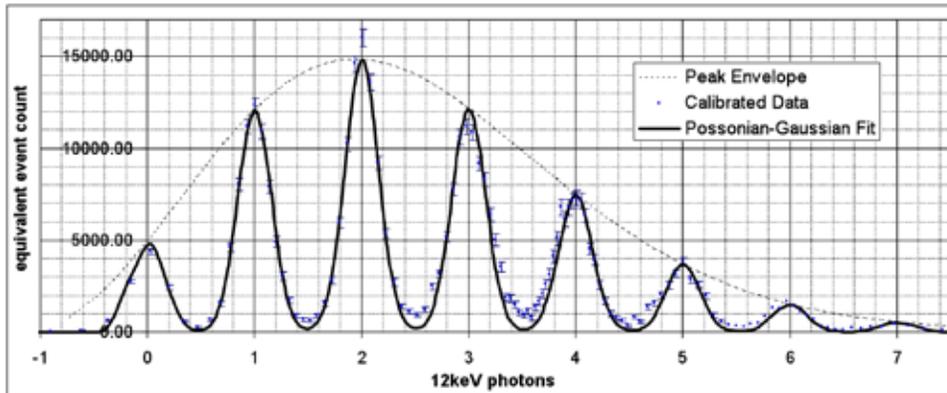


Beam mechanically chopped at 2,000 Hz

16 kHz frame rate

3DX Linearity

Photon Counting

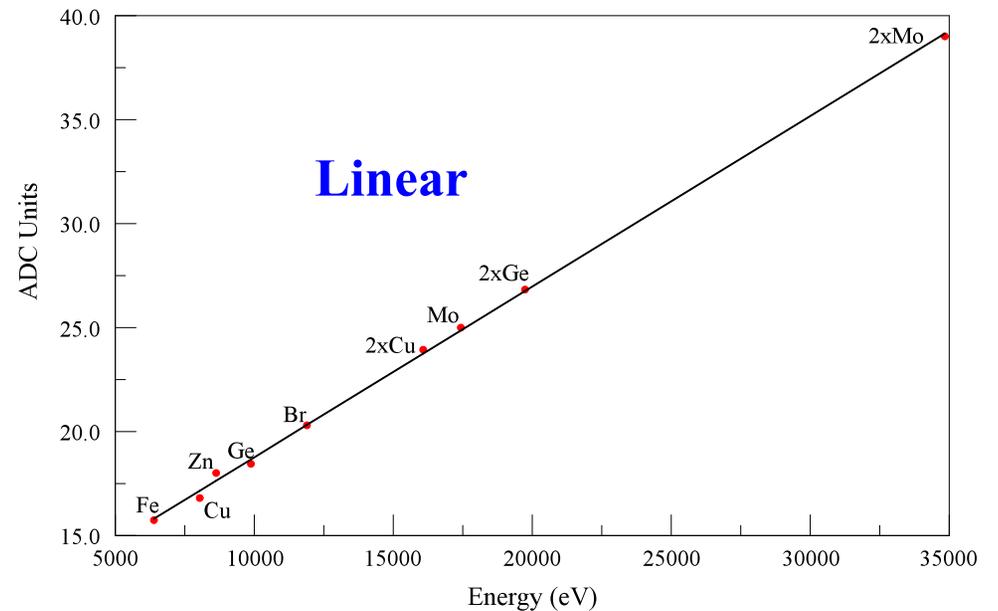


Pixel-level high/low gain bit

On-chip frame noise correction circuit

On-chip pedestal trimming

Second generation ready for testing



Summary

- CS-PAD camera #1 successfully operating in LCLS-XPP hutch
- Two more CS-PAD detectors will be made and installed in the LCLS-CXI hutch in early 2011
- Small area CS-PAD system planned for use in the LCLS-MEC
- Developing low-channel-count detectors based on the FEXAMPS chip for XPP and XCS hutches
- BNL detector system to be installed in the LCLS-XPP hutch in early 2011
- Developing and fabricating sensor for the LCLS-XCS hutch based on novel sensor concept proposed by Pavel Rehak of BNL
- Switcher and front-end circuit chips for the XCS sensor have been designed and are in fabrication